

Linear Algebra

Problem Set 3

2009

Due Wednesday, 25 March 2009 at 10:00 AM in EE207. Be sure to print your name and student ID on your homework.

1. An n by n matrix A is called *idempotent* if $A^2 = A$, where $A^2 = AA$.
 - (a) Show that if A is idempotent and invertible, then $A = I$.
 - (b) If A is idempotent, find the inverse of $I - cA$ (if possible) for some scalar c .
(What is the form of the inverse? Guess it.)
2. Let E be the n by n matrix each of whose entries is 1. What is the inverse of $I - E$?
3. Section 2.4, Problem 35

Elimination for a 2 by 2 block matrix: When you multiply the first block row by CA^{-1} and subtract from the second row, what is the “Schur complement” S that appears?

$$\begin{bmatrix} I & 0 \\ -CA^{-1} & I \end{bmatrix} \begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} A & B \\ 0 & S \end{bmatrix}.$$

Also, find a 2 by 2 block matrix X such that

$$\begin{bmatrix} A & B \\ 0 & S \end{bmatrix} = \begin{bmatrix} A & 0 \\ 0 & S \end{bmatrix} X.$$

4. With the results obtained in Problem 3, express $\begin{bmatrix} A & B \\ C & D \end{bmatrix}$ as the product of three 2 by 2 matrices. And then find the inverse of $\begin{bmatrix} A & B \\ C & D \end{bmatrix}$. (You only need to show it as the product of three matrices.)
5. Section 3.1, Problem 10
Which of the following subsets of \mathbf{R}^3 are actually subspaces?
 - (a) The plane of vectors (b_1, b_2, b_3) with $b_1 = b_2$.
 - (b) The plane of vectors with $b_1 = 1$.
 - (c) The vectors with $b_1 b_2 b_3 = 0$.
 - (d) All linear combinations of $\mathbf{v} = (1, 4, 0)$ and $\mathbf{w} = (2, 2, 2)$.
 - (e) All vectors that satisfy $b_1 + b_2 + b_3 = 0$.
 - (f) All vectors with $b_1 \leq b_2 \leq b_3$.
6. Section 3.1, Problem 4

The matrix $A = \begin{bmatrix} 2 & -2 \\ 2 & -2 \end{bmatrix}$ is a “vector” in the space \mathbf{M} of all 2 by 2 matrices.

Write down the zero vector in this space, the vector $\frac{1}{2}A$, and the vector $-A$.

What matrices are in the smallest subspace containing A ? (To answer this problem, you can simply show the general form of the matrices.)

7. Section 3.1, Problem 18

True or false (check addition in each case by an example).

- (a) The symmetric matrices in \mathbf{M} (with $A^T = A$) form a subspace.
 - (b) The skew-symmetric matrices in \mathbf{M} (with $A^T = -A$) form a subspace.
 - (c) The unsymmetric matrices in \mathbf{M} (with $A^T \neq A$) form a subspace.
8. What condition (equation) must be satisfied so that vector (b_1, b_2, b_3) is in the column space of A ?

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}.$$

9. Section 3.1, Problem 23

If we add an extra column \mathbf{b} to a matrix A , then the column space gets larger unless _____. Give an example where the column space gets larger and an example where it doesn't. Why is $A\mathbf{x} = \mathbf{b}$ solvable exactly when the column space *doesn't* get larger—it is the same for A and $[A \ \mathbf{b}]$?

10. Section 3.1, Problem 27

True or false (with a counterexample if false):

- (a) The vectors \mathbf{b} that are not in the column space $C(A)$ form a subspace.
- (b) If $C(A)$ contains only the zero vector, then A is the zero matrix.
- (c) The column space of $2A$ equals the column space of A .
- (d) The column space of $A - I$ equals the column space of A .