Solution to Problem Set 6

1.

(a)
$$\begin{bmatrix}
1 & 0 & 1 \\
A & 0 & 1 & 0 \\
1 & 0 & -1
\end{bmatrix} = \begin{bmatrix}
-1 & 1 & 1 \\
0 & 0 & -2 \\
1 & -1 & 1
\end{bmatrix} \Rightarrow A = \begin{bmatrix}
0 & 1 & -1 \\
-1 & 0 & 1 \\
1 & -1 & 0
\end{bmatrix}$$
(b)
$$\text{Let } B = \begin{bmatrix}
1 & 0 & 1 \\
0 & 1 & 0 \\
1 & 0 & -1
\end{bmatrix}$$

$$A' = B^{-1}AB = \begin{bmatrix}
0 & 0 & 1 \\
0 & 0 & -2 \\
-1 & 1 & 0
\end{bmatrix}$$

2.

$$1 \xrightarrow{L} x \; ; \; x \xrightarrow{L} 1 + x^2 \; ; \; x^2 \xrightarrow{L} 2x + x^3$$

$$\therefore A \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow A = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\therefore \text{the basis for the range of L is} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 0 \\ 1 \end{bmatrix}$$

3.

(a) we need to show that 
$$T^{-1}(T(x)) = x$$
&  $T(T^{-1}(x)) = x$   
 $T^{-1}(T(x)) = A^{-1}(Ax + b) - A^{-1}b = x + A^{-1}b - A^{-1}b = x$   
 $T(T^{-1}(x)) = A(A^{-1}x - A^{-1}b) + b = x - b + b = x$   
(b)  
Let  $L_1$ : 法向量 $m_1$   $L_2$ : 法向量 $m_2$ 

$$T(m_1) = Am_1 + b$$
  $T(m_2) = Am_2 + b$ 

if 
$$L_1//L_2 \Rightarrow m_1 = m_2 \Rightarrow T(m_1) = T(m_2)$$

轉換後的法向量仍然相同 $\Rightarrow L_1'/L_2'$ 

4.

No, it is not possible to find the basis B.

$$\because L = B [L]_B B^{-1}$$

if 
$$[L]_B = I$$
 ,  
then  $L = BB^{-1} = I$ 

but L is rotate matrix (45 degrees).

5. (a)
$$\begin{bmatrix}
1 & -2 \\
-3 & 4
\end{bmatrix} [v]_B = \begin{bmatrix}
-7 & -5 \\
9 & 7
\end{bmatrix} [v]_C$$

$$\Rightarrow [v]_C = \begin{bmatrix}
2 & -1.5 \\
-3 & 2.5
\end{bmatrix} [v]_B$$

$$\Rightarrow M = \begin{bmatrix}
2 & -1.5 \\
-3 & 2.5
\end{bmatrix}$$
(b)
$$[T]_C = M[T]_B M^{-1} = \begin{bmatrix}
13 & 8 \\
-18 & -11
\end{bmatrix}$$

6. 4.1(17)

If S is the subspace of  $\mathbb{R}^3$  containing only the zero vector, then  $\mathbb{S}^\perp$  is  $\mathbb{R}^3$ .

If S is spanned by (1,1,1), then  $S^{\perp}$  is spanned by (1,-1,0) and (1,0,-1), which is nullspace of S.

If S is spanned by (2,0,0) and (0,0,3), then  $S^{\perp}$  is spanned by (0,1,0), which is nullspace of S.

 $7. \ 4.1(28)$ 

- (a) (1, -1, 0) is in both planes. Normal vectors are perpendicular, but planes still intersect!
- (b) Need three orthogonal vectors to span the whole orthogonal complement.
- (c) Lines can meet without being orthogonal.

8. 4.1(30)

When AB = 0, the column space of B is contained in the nullspace of A. Therefore the dimension of  $C(B) \leq dimension$  of N(A). This means  $rank(B) \leq 4 - rank(A)$ .

9. 4.2(13)

$$p = (1, 2, 3, 0). \ P = square \ matrix = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

10. 4.2(19)

For any choice,  
say 
$$(1,1,0)$$
 and  $(2,0,1)$ , the matrix  $P$  is 
$$\begin{bmatrix} 5/6 & 1/6 & 1/3 \\ 1/6 & 5/6 & -1/3 \\ 1/3 & -1/3 & 1/3 \end{bmatrix}$$
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